1. INTRODUCTION

In response to physical limitations, hardware has changed significantly during the past two decades. As the database community, we have no chance but adapt to those changes in order to benefit from these and further hardware advances.

Two strategies to deal with the change have proven particularly successful. To avoid hitting the memory wall, modern engines compile queries into native machine code [3]; this way, data can be kept longer in registers and performance-limiting memory I/Os can be avoided. To escape the power wall, the use of heterogeneous and massively parallel architectures has been proposed; graphics processors (GPUs) in particular can deliver spectacular compute performance at a very attractive power footprint. But while both these strategies are very successful and well understood, it is surprisingly difficult to bring both together without losing much of their benefit.

In this demo, we showcase DogQC, the query compiler that we develop at TU Dortmund University. DogQC includes the Lane Refill and Push-Down Parallelism techniques to combat divergence effects that are the root cause for the above mentioned difficulty. The two techniques very effectively avoid resource under-utilization on graphics processors, while leveraging the bandwidth efficiency of compiled code. In practice, DogQC’s anti-divergence measures can improve query performance by several factors.

1.1 Divergence in GPU-Based Execution

The root cause for the discrepancy between query compilation and (heterogeneous) parallelism is divergence. To understand the effect, consider the plan excerpt from TPC-H Q10 shown here on the right. A query compiler will attempt to compile the marked plan region into a straight-line sequence of code, a pipeline. The motivation to do so is to propagate tuple data within registers, rather than spilling data to (slow) memory.

During execution, not all lineitem tuples will actually traverse the full pipeline. Some tuples might instead be eliminated by operators such as filter $\sigma$ or join $\Join$. If this happens, a sequential processor will immediately abort the pipeline, continue with the next input item, and hence keep CPU efficiency at peak.

Data-parallel execution back-ends, by contrast, do not have the option of aborting a pipeline early, unless all tuples in the same batch of work are eliminated.

Figure 1 illustrates this effect for a GPU-based back-end (assuming a batch—or “warp”—size of eight for illustration purposes). In some warp iteration, only warp lanes 1, 5, and 7 might have passed the filter $\sigma$, leaving the five remaining warp lanes inactive (indicated as dashed arrows). The following join de-activates another two warp lanes, bringing GPU efficiency down to $1/8$ in this example.

The resulting GPU under-utilization is even worse in real settings. To scan a lineitem table with 150 million rows, actual GPUs will require 5 million warp iterations, each consisting of 32 warp lanes. Although $\sigma$ filters out about $2/3$ of all rows, it is extremely unlikely that all lanes within a warp become inactive. Therefore, (almost) all 5 million warp iterations proceed into the join operator $\Join$. Only 1% of the remaining rows find a match during the join. In an actual data set, 2.9 million rows remain after the join, but...
they are spread across 1.1 million warp iterations. Ideally, the projection \( \pi \) and aggregation \( \text{aggr} \) operators could have been processed by only 2.9 M/32 = 90 K warp iterations. In other words, state-of-the-art query compilation techniques will leave 92% of the GPU’s processing capacity unused.

1.2 GPU Query Compiler DogQC

GPU code generated by our query compiler DogQC\(^1\) leverages Lane Refill and Push-Down Parallelism techniques to counter divergence effects like the ones we described. In the rest of this demonstration proposal, we will give a high-level idea of the Lane Refill technique (Section 2), then describe how we intend to demonstrate the internals of the DogQC engine at VLDB (Section 3); in Section 4, we report on experimental results for DogQC before we wrap up in Section 5. More details on the Lane Refill and Push-Down Parallelism mechanisms can be found in the respective full paper [1].

2. LANE REFILL TECHNIQUE

Divergence effects (here: filter divergence) are a consequence of the SIMT, “single instruction, multiple threads,” execution paradigm embodied in all modern graphics processors. A number of threads (or lanes, typically 32 of them) is grouped into a warp. During execution, all lanes within a warp execute the same GPU instruction.

The SIMT model encounters a problem whenever some lanes or data elements need a different amount or kind of processing than others. In such situations, control flows will diverge. Since all lanes within a warp still execute the same instruction, lanes will be turned inactive and their computation result will be discarded. As illustrated above, this can result in resource under-utilization.

To illustrate the severity of this effect, we instrumented the query plan shown earlier (Figure 1) to monitor warp utilization at the plan point marked with a magnifying glass \( Q \). Figure 2 shows a histogram on the number of warps that have passed this plan stage with a warp utilization of 1, \ldots, 32 active lanes. It is easy to see that only a fraction of the available compute capacity is used; in most warps, only one or two out of 32 warp lanes performed actual work.

2.1 Balance Operators and Refill Buffers

To combat the situation, DogQC injects balance operators into the relational query plan. Code generated for these operators detects warp under-utilization at runtime. Whenever utilization drops below a configured threshold, the state of all remaining active lanes is suspended to a refill buffer and the pipeline starts over with a fresh set of input tuples.

\(^1\)https://github.com/Henning1/dogqc

Figure 2: Lane activity profile with filter divergence.

Figure 3 illustrates this for three successive warp iterations ① through ③. Since only 2, 1, and 3 lanes remained active in these iterations (respectively), their state is flushed to the refill buffer. After flushing, each of those warp iterations is terminated and processing starts over with the next set of input tuples.

2.2 Refilling

As soon as a sufficient number of lane states has been stored to the refill buffer, the buffer can be used to refill lanes that have become inactive. This time, the under-utilized warp iteration is not terminated but continues processing with full utilization after refilling. This is visualized in Step ④ of Figure 3. Here, only two out of eight warp lanes remained active after the downstream join operator. Using the refill buffer, the remaining six warp lanes can be filled with useful work, resulting in full warp utilization upstream.

Implementation-wise, flushing and refilling are backed up in DogQC by CUDA’s \_ballot_sync, \_popc ("population count"), and shuffling primitives. These primitives are highly efficient; balance operators will cause little overhead even when only few warps go below the utilization threshold.

2.3 Effect of Lane Refill

Lane Refill brings warp utilization back to a high compute efficiency. Following the balancing operator, all executed warps (except for the last warp in each grid block) are guaranteed to have a warp utilization above the configured threshold.

In Figure 4, this is illustrated with a histogram for the same plan point that we profiled earlier (Figure 2), but this time with a balance operator applied. The histogram confirms that (a) (almost) no warps exist with a utilization below 26 lanes (the threshold we configured); and (b) the total number of executed warps has dropped by a factor of about ten. In terms of overall execution performance, lane
refill will improve execution times by about 2–3x for the example plan shown in Figure 1.

3. DEMO SETUP

Our demonstration at VLDB will enable visitors to look under the hoods of the DogQC query compiler, with a focus on anti-divergence techniques.

DogQC provides mechanisms to visualize generated query plans (we leverage the dot\(^2\) utility for this purpose), which demo spectators can use for inspection. An example of an actual query plan is shown in Figure 5(a) for the TPC-H Q10 plan sketched in Figure 1. As part of the demo, visitors will be able to freely place balance operators into DogQC-generated query plans and observe their effects (in Figure 5(b), a balance operator—highlighted in red—has been injected, corresponding to the \(Q\) marker in Figure 1).

Balance operators (if placed properly) will have an immediate effect on query execution speeds, which demo visitors will be able to verify with TPC-H and other data sets.

To inspect the inner workings of anti-divergence techniques, DogQC is equipped with profiling mechanisms that visualize GPU lane utilization. At the demo, visitors will be able to generate histogram graphs like those in Figures 2 and 4 for their own queries and at arbitrary points in the query plan.

Finally, demo visitors will be able to verify the utilization of further GPU resources, such as registers, memories, or caches.

3.1 Flavors of Divergence

Filter divergence as described in this proposal and illustrated in Figure 1 is just one flavor of divergence that DogQC provides support for. Lane Refill and Push-Down Parallelism are the two main techniques that we use in DogQC to combat divergence, including all of the following types of divergence:

**Variable-Length Data.** The size of an attribute may vary across different entities. Strings are a prime example of this divergence flavor. If strings are evaluated character by character, warp lanes that process shorter strings will finish earlier than other lanes.

**Skewed Data Distributions.** When processing joins, some attribute values may find more join partners than others. Again, this may cause some lanes to run out of work earlier than other lanes.

**Computation Divergence.** As a secondary effect of data properties, divergence may occur during computations. E.g.,

3https://www.graphviz.org/

Figure 4: Lane activity profile with lane refill buffer to consolidate filter divergence.

Figure 5: DogQC query plans corresponding to the TPC-H Q10 plan sketched in Figure 1. Left: query plan without balance operators; right: plan with balance operator injected after the join operator (corresponding to \(Q\) in Figure 1).

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hash collisions will result in longer processing times for some warp lanes.

For the demo, we will prepare datasets and queries that highlight the individual flavors of divergence. Visitors will be free, of course, to discover their own divergence effects based on TPC-H data and their own queries.

Divergence effects arise also in further scenarios that do not directly apply to DogQC. Lang et al. [2] report on divergence effects that may arise in (CPU-based) SIMD environments. Sha et al. [5] use similar techniques to combat divergence when traversing graphs using GPUs.

4. EVALUATION

With DogQC, we provide a query compiler with a wide range of SQL functionality; sufficient to support the 22 queries from the TPC-H benchmark set.

4.1 TPC-H Performance

To assess the benefits of measures to contain divergence, we performed a series of measurements with the TPC-H benchmark set. Our measurements were based on an NVIDIA RTX2080 GPU with 46 Streaming Multiprocessors and 8 GB GPU memory, installed in a host system with an Intel i7-9800X GPU and 32 GB of main memory. As a reference, we compared DogQC with the hybrid CPU/GPU system OmniSci [4].
Our benchmark results are depicted in Figure 6. For each of the 22 TPC-H queries, the bars indicate query execution time assuming that the data set is resident in GPU memory.

For OmniSci, we report the total wall clock time needed to execute the query as well as the amount of time spent on GPU processing. OmniSci is a hybrid execution engine, meaning that both, CPU and GPU, will be used to jointly answer the query. As can be seen in the figure, several queries can, in fact, not benefit much from GPU acceleration in OmniSci. Also mind that OmniSci could successfully execute only 13 of the 22 TPC-H benchmark queries.

The focus of this demonstration is on avoiding divergence effects. To this end, we prepared a version of DogQC where the divergence-related optimizations can be turned off (if appropriate, see below). In the graph, this is reported as “naive.” As can be seen in the figure, the mitigation of divergence will result in a significant performance improvement for some queries, while never having any negative impact on any query. DogQC can run all 22 TPC-H queries entirely on the GPU (benefits from hybrid CPU/GPU processing would be orthogonal to divergence mitigation).

A secondary benefit of divergence handling in DogQC cannot directly be observed in the figure. An important flavor of divergence stems from the processing of (variable-length) strings. Existing systems, including OmniSci, circumvent the problem and apply dictionary encoding on all string data. The resulting overhead on ingestion speed and memory requirement cannot be inferred from Figure 6. DogQC, by contrast, can naturally handle variable-length data, including strings (also in its “naive” configuration). See [1] for details.

5. SUMMARY
Divergence effects can seriously impair the performance potential of modern, data-parallel execution platforms such as GPUs. With help of the Lane Refill and Push-Down Parallelism techniques, our query compiler DogQC can combat divergence effects and restore processing efficiency.

DogQC supports the full TPC-H benchmark set. In the demo, visitors will be able to experiment with DogQC, state their own queries, and watch the inner workings of DogQC.

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6. REFERENCES